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Revisiting Manin's theorem of the kernel

DANIEL BERTRAND⁽¹⁾

À la mémoire de Hiroshi Umemura

ABSTRACT. — In the first part of the paper, we use Manin's map to establish a finiteness result linking rational sections of an elliptic scheme and solutions of Painlevé VI equations. The rest of the paper concerns abelian schemes over curves, and presents a survey of the various statements encompassed by Manin's theorem of the kernel.

RÉSUMÉ. — Dans la première partie de ce texte, on établit au moyen de l'application de Manin un énoncé de finitude reliant les sections d'un schéma elliptique et les solutions des équations de Painlevé VI. Le reste de l'article concerne le théorème du noyau de Manin dans le cadre d'un schéma abélien sur une courbe, et passe en revue les divers énoncés connus sous cette appellation.

1. A motivation from Painlevé VI equations

1.1. The Manin map in the elliptic case

Consider the Gauss–Legendre elliptic scheme $(E) : \eta^2 = \xi(\xi - 1)(\xi - t)$ over the complex curve $S = \mathbf{P}_1 \setminus \{0, 1, \infty\}$, and let the derivation $\partial = d/dt$ of \mathcal{O}_S act on differential forms on E/S by setting $\partial \xi = 0, \partial(fd\xi) = \frac{\partial f}{\partial t} \cdot d\xi$ for the coordinate system (t,ξ) . Then, $\omega = \frac{d\xi}{\eta} \in H^0(E, \Omega^1_{E/S}) \subset H^1_{dR}(E/S)$ satisfies

$$L(\omega) = \frac{1}{2}d\left(\frac{\eta}{(\xi - t)^2}\right) \quad \text{where} \quad L := t(1 - t)\frac{d^2}{dt^2} + (1 - 2t)\frac{d}{dt} - \frac{1}{4}.$$

Keywords: abelian varieties, Manin maps, Gauss-Manin connections, Mumford-Tate groups, Painlevé VI equations.

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So, the class of $L(\omega)$ in $H^1_{dR}(E/S)$ vanishes, and the periods $\int_{\gamma} \omega, \gamma \in H_{1,B}(E/S)$, generate over \mathbb{C} the space of solutions of $L(\cdot) = 0$ (note that $\partial(\int_{\gamma} \omega) = \int_{\gamma} \partial \omega$).

Let now $y(t) := (\xi(t), \eta(t)) \in E(S)$ be a section of E/S, and consider with Manin [18] the (multivalued) elliptic logarithm of y

$$u(t) = \int_0^{y(t)} \omega = \ell n_E(y(t)) \in \operatorname{Lie} E(\widetilde{S}^{\operatorname{an}}).$$

Since the indeterminacies of u(t) are the periods of ω , which are killed by L, and since u(t) has moderate growth near its singularities, L(u(t)) is a well-defined element of the function field $K = \mathbb{C}(S)$, and in fact lies in \mathcal{O}_S . We therefore obtain a *Manin map*:

$$\boldsymbol{\mu}_E: E(S) \longrightarrow \mathcal{O}_S: y \longmapsto \boldsymbol{\mu}_E(y) := L(u),$$

which, taking into account the exact form above and fudge factors coming from derivation of the boundary (∂ no longer commutes with \int_0^y : concretely, $\partial(\int_{\infty}^{\xi(t)} f d\xi) - \int_{\infty}^{\xi(t)} \partial(f d\xi) = \xi'(t) f(\xi(t))$), is given by

$$y = (\xi, \eta) \longmapsto \mu_E(y) = \frac{1}{2} \frac{\eta}{(\xi - t)^2} + \left(t(1 - t) \frac{\xi'}{\eta} \right)' + t(1 - t) \frac{\xi'}{\eta} \cdot \frac{\eta'}{\eta},$$

Since ω is an invariant form, μ_E is a group homomorphism. Since the target space is uniquely divisible, its kernel contains the torsion part E^{tor} of E, and Manin's theorem of the kernel asserts in this case that

$$\operatorname{Ker}(\boldsymbol{\mu}_E) = E^{\operatorname{tor}}(S).$$

The formula above shows that $\boldsymbol{\mu}_E$ extends to any differential extension (F,∂) of K. In the language of differential algebraic groups (see [9]), $\boldsymbol{\mu}_E$: $E \to \mathbb{G}_a$ is a *differential algebraic additive* character of order 2, defined over K. Its kernel over F may strictly contain $E^{\text{tor}}(F)$: for instance, the transcendental section y(t) defined, locally and in standard notation, by $\wp(\omega_1(t) + \sqrt{2}\omega_2(t))$ is killed by $\boldsymbol{\mu}_E$.

1.2. Link with Painlevé VI

Apart from Proposition 1.1 below, this section follows [20]. For links with the Galois theory of Painlevé equations, see [21] (and [10] for the Picard– Painlevé solution mentioned just above). The P VI equations depend on four complex parameters $\alpha, \beta, \gamma, \delta$, and are given by

$$\begin{split} \frac{\mathrm{d}^2\xi}{\mathrm{d}t^2} &= \frac{1}{2} \bigg(\frac{1}{\xi} + \frac{1}{\xi - 1} + \frac{1}{\xi - t} \bigg) \bigg(\frac{\mathrm{d}\xi}{\mathrm{d}t} \bigg)^2 - \bigg(\frac{1}{t} + \frac{1}{t - 1} + \frac{1}{\xi - t} \bigg) \frac{\mathrm{d}\xi}{\mathrm{d}t} \\ &+ \frac{\xi(\xi - 1)(\xi - t)}{t^2(t - 1)^2} \bigg(\alpha + \beta \frac{t}{\xi^2} + \gamma \frac{t - 1}{(\xi - 1)^2} + \delta \frac{t(t - 1)}{(\xi - t)^2} \bigg). \end{split}$$

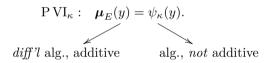
Following R. Fuchs and Manin, this is rewriten in terms of points $y = (\xi, \eta)$ in E(F) as:

$$t(1-t)\boldsymbol{\mu}_{E}(y) = \alpha \eta + \beta t \frac{\eta}{\xi^{2}} + \gamma(t-1)\frac{\eta}{(\xi-1)^{2}} + \left(\delta - \frac{1}{2}\right)t(t-1)\frac{\eta}{(\xi-t)^{2}}.$$

Set $\kappa = (\kappa_0, \kappa_1, \kappa_2, \kappa_3) := (\alpha, -\beta, \gamma, \frac{1}{2} - \delta)$, let $e_0 = 0_E, e_1 = (0, 0), e_2 = (1, 0), e_3 = (t, 0)$ be the 2-torsion of E(S), and consider the rational function ψ_{κ} on E given by

$$y \mapsto \psi_{\kappa}(y) = \frac{1}{t(t-1)} \sum_{i=0}^{3} \kappa_i \ \eta(y+e_i).$$

Then, P VI finally becomes: find a local section y(t) of E/S^{an} such that



The following result reflects the incompatibility of these properties. The statement itself is inspired by the theme of "unlikely intersections" in diophantine geometry.

PROPOSITION 1.1. — For any finite extension K' of $\mathbb{C}(t)$, there are only finitely many points $y = (\xi, \eta) \in E(K')$ such that ξ solves some (unspecified) P VI equation.

Proof. — We will rely on the following facts from Manin's Mordell paper.

- (i) By Mordell–Weil, the set $\{\boldsymbol{\mu}_E(y), y \in E(K')\}$ lies in a finite dimensional \mathbb{C} -subspace of K', while the set $\{y \in E(K'), \boldsymbol{\mu}_E(y) = 0\}$ is finite; indeed, by the theorem of the kernel, the latter one coincides with $E^{\text{tor}}(K')$, which is finite.
- (ii) (cf. [18, §7, Prop. 6]). Let V be a finite dimensional \mathbb{C} -vector subspace of K'(E). Then, the set $\{y \in E(K'), \exists f^y \in V \setminus \{0\}, f^y(y) = 0\}$ has bounded height (and is therefore finite, since E/S is not isoconstant). Notice that once V is fixed, the functions f^y of the statement are allowed to depend on y.

To prove the proposition, we may restrict to the points $y \in E(K')$ such that $\boldsymbol{\mu}_E(y) \neq 0$, since in view of the second part of (i), the other ones form a finite set. Let then V be the finite-dimensional subspace of K'(E) generated over \mathbb{C} by the 4 elements $\eta(\cdot + e_i)$ of K'(E) and by the finitely generated subgroup $\Gamma = t(t-1)\boldsymbol{\mu}_E(E(K'))$ of K'. By the formula above, the ξ -coordinate of a point y in E(K') satisfies some P VI equation only if there exist $\mu^y \in \Gamma$ and complex numbers $\kappa_0^y, \ldots, \kappa_3^y$, depending on y but not all 0 by our restriction, such that $\kappa_0^y \eta(y + e_0) + \cdots + \kappa_3^y \eta(y + e_3) - \mu^y = 0$. Now, consider the rational function $f^y(\cdot) = \sum_{i=0,\ldots,3} \kappa_i^y \eta(\cdot + e_i) - \mu^y$, which lies in V. In view of their poles, 1 and the 4 functions $\eta(\cdot + e_i)$ are linearly independent over K', so the function f^y is not 0, and we conclude by (ii).

2. Manin maps

This section describes various "Manin maps" occuring in the literature. Their kernels will all be compared in the next section, see Theorem 3.1, which is the main statement of this survey. For questions related to their images, see Section 3.3.

2.1. The Gauss–Manin connections

From now on, the setting is as follows: the base is a smooth irreducible affine curve S over the complex numbers \mathbb{C} , with function field $K = \mathbb{C}(S)$ and coordinate ring $O_S = \mathbb{C}[S]$. The results will be insensitive to finite base changes, which we tacitly perform when needed. We fix a non-zero vector field over S, and denote by ∂ the associated derivation on K. We can assume that the ring \mathcal{D} of differential operators on S is $O_S[\partial]$. Given a locally free \mathcal{O}_S -module V with an (integrable) connection ∇_V , we write D_V , or just D, for the contraction of ∇_V with ∂ . This is as an additive endomorphism of Vsatisfying the Leibniz rule, which naturally extends to an action of \mathcal{D} on V: if $L = \sum_i a_i \partial^i$, then $L(v) = \sum_i a_i (D_V)^i(v)$. We denote by 1 the D-module \mathcal{O}_S , with $\nabla = d$.

2.1.1. Extensions of *D*-modules

In the category of *D*-modules, extensions
$$(W, \nabla_W)$$

 $0 \longrightarrow (V, \nabla_V) \longrightarrow (W, \nabla_W) \longrightarrow (\mathcal{O}_S, d) \longrightarrow 0$

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of 1 by (V, ∇_V) can be concretely described as follows. For V free of rank n, fix a basis of V over O_S , and choose $w \in W$ projecting to $1 \in O_S$. Then, $D_V = \partial - B$ for some $B \in \mathfrak{gl}_n(O_S)$, while the matrix for ∇_W is $\begin{pmatrix} B & c \\ 0 & 0 \end{pmatrix} \in \mathfrak{gl}_{n+1}(O_S)$ for the column vector $c = D_W(w) \in (O_S)^n = V(S)$. A fundamental matrix of solutions of D_W has the same shape $\begin{pmatrix} B & u \\ 0 & 1 \end{pmatrix}$, where \mathcal{B} is a fundamental matrix of solutions of D_V , and u is a solution of the inhomogenous system $D_V(u) = c$. Replacing w by w+v with $v \in V(S)$ replaces c by $c+D_V(v)$, and u by u+v. It follows that the isomorphism class of the extension W in $\operatorname{Ext}_{D-\operatorname{mod}}(1, V)$ is given by the class of c in $V(S)/D_V(V(S))$, or more precisely (cf. [13, Prop. 1.1.1]) in the first cohomology group of the complex $V \xrightarrow{D_V} V$ (in degrees 0 and 1), and we have (cf. [4, §1], at least when $K = \mathbb{C}(\mathbb{P}_1)$):

$$\operatorname{Ext}_{D-\operatorname{mod}}(\mathbb{1}, V) \simeq H^1(V \xrightarrow{D_V} V) \simeq V(S)/D_V(V(S))$$

Analytically (cf. [13, Prop. 1.6.1]), this \mathbb{C} -vector space is given by $H^1(S, V^D)$ for the local system of solutions of D_V ; it has finite dimension, depending only on n and $\chi(S)$ when ∇_V is fuchsian (Deligne's formula, cf. [4, Lem. 2]). Anyway, the extension W splits if and only if $c = D_V(v)$ for some v in V(S), or equivalently, if and only if u is a \mathbb{C} -linear combination of the columns of the matrix \mathcal{B} , up to addition of an element of $(O_S)^n$.

Considering the connection ∇_V^{\vee} on the dual of V, one deduces that $\operatorname{Ext}_{D-\operatorname{mod}}(V,1) \simeq H^1(V^{\vee} \xrightarrow{D_{V^{\vee}}} V^{\vee})$. In particular, if $L \in \mathcal{D}$ is a non zero differential operator and V is the dual of $\mathcal{D}/\mathcal{D}L$, an extension of 1 by V corresponds to an inhomogeneous equation $L(u) = \mu$, for some $\mu \in O_S$, and its isomorphism class is given by the image $\bar{\mu}$ of μ in $O_S/L(O_S)$, cf. [4, Lem. 4]. It splits if and only if u is the sum of a solution of $L(\cdot) = 0$ and of an element of O_S . In reflection to the fact that cyclic vectors do not behave well under the constructions of linear algebra, the case $\mu = 0$ should be treated in matrix terms to justify that it represents the trivial extension. Obviously, $\mu = 0$ implies that $\bar{\mu} = \bar{0}$. It is a remarkable feature that under further (Hodge theoretic) constraints, the representative 0 of $\bar{0}$ will appear naturally in what follows, cf. Section 2.3, and the end of Section 3.3.

2.1.2. Gauss-Manin

Let now $A \to S$ be an abelian scheme of relative dimension g, with generic fiber A_K . The results will be invariant under isogenies and finite base extensions, which we again tacitly perform when needed. In particular, we can assume that the fixed "part", i.e. the K/\mathbb{C} trace, $A_0/\mathbb{C} = \text{Tr}_{K/\mathbb{C}}(A_K)$ of A is a direct summand. The group

$$A_0(\mathbb{C})^{\mathrm{div}} = \{ y \in A(S), \exists \ 0 \neq k \in \mathbb{Z}, k.y \in A_0(\mathbb{C}) \}$$

contain the torsion sections, and we call its elements the *constant sections* of A/S.

Let further $y \in A(S) \simeq A_K(K)$ be a section of A/S, and let $\mathbb{A}_y = [\mathbb{Z} \xrightarrow{1 \mapsto y} A]$ be the associated smooth S-1-motive, see [15]. This is an extension of $[\mathbb{Z} \to 0]$ by $[0 \to A]$, or said more briefly of \mathbb{Z} by A. To keep track of variances, note that its Cartier dual \mathbb{A}_y^{\vee} is the extension of the dual abelian variety A^{\vee} by \mathbb{G}_m parametrized by $y \in A^{\vee \vee} \simeq A$.

The Betti realizations of these 1-motives can be described as follows: $T_B(A)$ is the kernel of the exponential morphism \exp_A : Lie $(A) \to A$ over S^{an} , while $T_B(\mathbb{A}_y)$ is the inverse image under \exp_A of $\mathbb{Z}.y$. As such, they are \mathbb{Z} -local systems over S^{an} of ranks 2g, 2g + 1. The de Rham realizations, $T_{dR}(A)$, $T_{dR}(\mathbb{A}_y)$ (see [15, 10.1.7], and Section 2.3 below) are $\mathcal{O}_{S^{-1}}$ modules, which, after extension to $\mathcal{O}_{S^{an}}$, become isomorphic to $T_B(A) \otimes \mathcal{O}_{S^{an}}$, $T_B(\mathbb{A}_y) \otimes \mathcal{O}_S$, and so, carry connections $\mathrm{id} \otimes d$. As alluded to in Section 1, one checks that these actually descend to $T_{dR}(A)$, $T_{dR}(\mathbb{A}_y)$, which are therefore endowed with canonical connections $\nabla_A, \nabla_{\mathbb{A}_y}$, called (together with their duals) the Gauss-Manin connections. By construction, their spaces of horizontal sections are given by the Betti realizations, tensored with \mathbb{C} .

We are now ready to define the Manin map, or more accurately, the two types of Manin maps which occur in the literature. For lack of a better phrasing, I will call them differential algebraic (they are Manin's original ones [18], as taken up by Buium [9], see also [8]), and cohomological (as extracted by Coleman [13] from Manin's construction). We will begin with the latter ones, which are easier to describe and lead to sharper results. Note that I call them cohomological not because of de Rham cohomologies (these occur in both types), but because their targets are the H^1 's of complexes $V \xrightarrow{D_V} V$.

2.2. The cohomological Manin maps

The description of the local system $T_B(\mathbb{A}_y)$ shows that $T_{dR}(\mathbb{A}_y)$ lies in $\operatorname{Ext}_{D-\operatorname{mod}}(\mathbb{1}, T_{dR}(A))$:

$$0 \longrightarrow T_{\mathrm{d}R}(A) \longrightarrow T_{\mathrm{d}R}(\mathbb{A}_y) \longrightarrow (\mathcal{O}_S, d) = \mathbb{1} \longrightarrow 0.$$

but it will be more convenient to consider the dual connections on $H^1_{dR}(A) = (T_{dR}(A))^{\vee}$, $H^1_{dR}(\mathbb{A}_y) = (T_{dR}(\mathbb{A}_y))^{\vee}$. These sit in an exact sequence of *D*-modules:

$$0 \longrightarrow \mathbb{1} \longrightarrow H^1_{\mathrm{d}R}(\mathbb{A}_y) \xrightarrow{\pi} H^1_{\mathrm{d}R}(A) \longrightarrow 0.$$

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So, $H^1_{dR}(\mathbb{A}_y)$ is a *D*-module extension of $H^1_{dR}(A)$ by $\mathbb{1}$. We denote by $\mathcal{M}(y)$ its isomorphism class in $\operatorname{Ext}_{D-\operatorname{mod}}(H^1_{dR}(A),\mathbb{1})$, and by \mathcal{M} (or when needs be, \mathcal{M}_A):

$$\mathcal{M}: A(S) \ni y \longmapsto \mathcal{M}(y) := [H^1_{\mathrm{d}R}(\mathbb{A}_y)] \in \mathrm{Ext}_{D-\mathrm{mod}}(H^1_{\mathrm{d}R}(A), \mathbb{1})$$
$$\simeq T_{\mathrm{d}R}(A)(S)/D(T_{\mathrm{d}R}(A)(S))$$

the corresponding map. This cohomological Manin map is \mathbb{Z} -linear and takes values in a \mathbb{C} -vector space, so the torsion sections lie in its kernel. In fact, if y is a constant section, the D-module $\mathcal{M}_{A_0}(y)$ is isomorphic to a direct sum of $\mathbb{1}$'s, and so, $A_0(\mathbb{C})^{div}$ is always contained in the kernel of \mathcal{M}_A . In this situation, the theorem of the kernel (see [13, Thm. 1.4.3], and Theorem 3.1 (i) below) is:

$$\operatorname{Ker}(\mathcal{M}) = A_0(\mathbb{C})^{\operatorname{div}}.$$

In [13], Coleman pointed out that the following sharper statement would suffice to justify Manin's proof of Mordell, cf. [19]. Let $\Omega = H^0(A, \Omega^1(A/S)) \hookrightarrow$ $H^1_{\mathrm{d}R}(A)$ be the \mathcal{O}_S -module of relative differential forms of the 1st kind on A/S. It is not a *D*-submodule (unless the Kodaira map is trivial, i.e. when $A = A_0$, cf. [3]), and we denote by $[\Omega]$ the *D*-submodule of $H^1_{\mathrm{d}R}(A)$ generated by Ω . Let $\mathcal{M}_{|[\Omega]}(y) \in \mathrm{Ext}_{D-\mathrm{mod}}([\Omega], 1)$ be the isomorphism class of the restriction to $[\Omega]$ of the extension $\mathcal{M}(y)$. Then

$$\mathcal{M}_{|[\Omega]}: A(S) \ni y \longmapsto \mathcal{M}_{|[\Omega]}(y) \in \operatorname{Ext}_{D-\operatorname{mod}}([\Omega], \mathbb{1})$$

is a less precise cohomological Manin map: its kernel clearly contains that of \mathcal{M} . Coleman asked and Chai [12] proved that these kernels

$$\operatorname{Ker}(\mathcal{M}_{|[\Omega]}) = \operatorname{Ker}(\mathcal{M})$$

actually coincide (see Theorem 3.1(ii)).

More generally, let $i_V : V \hookrightarrow H^1_{dR}(A)$ be any *D*-submodule of $H^1_{dR}(A)$. Then $i_V^*(\mathcal{M}(y))$ gives a map $i_V^* \circ \mathcal{M} : A(S) \to \operatorname{Ext}_{D-\operatorname{mod}}(V, \mathbb{1})$. Chai also considered this broader situation (see [12], but also [5] and [11]), to which we will come back in Section 3.2.

Remark 2.1. — Here is a description of \mathcal{M} in terms of D-groups and their logarithmic derivatives, cf. [7]. Recall that a D-group is an algebraic group G/K endowed with an extension of ∂ to \mathcal{O}_G respecting the group structure of G. An abelian variety admits a D-group structure only if it is constant. On the other hand, the universal vectorial extension $\widetilde{A} \in \operatorname{Ext}_{\operatorname{alg.gr}/K}(A, W_A)$ of A:

$$0 \longrightarrow W_A \longrightarrow \widetilde{A} \longrightarrow A \longrightarrow 0,$$

with $W_A = H^1(A, \mathcal{O}_A)^{\vee} \simeq (\operatorname{Ext}(A, \mathbb{G}_a))^{\vee}$ of dimension g, has a unique D-group structure. Now, $T_{\mathrm{d}R}A$ is given by the Lie algebra $L\widetilde{A}$ of \widetilde{A} , and this

allows us to describe the map \mathcal{M} as follows: let $\partial \ell n_{\tilde{A}} : \tilde{A} \to L\tilde{A}$ be the logarithmic derivative on the *D*-group \tilde{A} . This induces on $L\tilde{A}$ the Gauss–Manin connection ∇_A of $T_{\mathrm{dR}}(A)$, contracted with ∂ . Now, lift the section $y \in A(S)$ to $\tilde{y} \in \tilde{A}(S)$, and consider the projection of $\partial \ell n_{\tilde{A}}(\tilde{y})$ to $L\tilde{A}(S)/D_A(L\tilde{A}(S))$. This projection is independent of the choice of the lift (since $\partial \ell n_{\tilde{A}}$ induces D_A on the vectorial subgroup $W_A \simeq LW_A$), and by [7], it coincides with $\mathcal{M}(y) \in \operatorname{Ext}_{D-\mathrm{mod}}(H^1_{\mathrm{dR}}(A), \mathbb{1})$, which is indeed the cokernel of the connection ∇_A on $H^1_{\mathrm{dR}}(A)^{\vee} \simeq T_{\mathrm{dR}}(A) \simeq L\tilde{A}$.

2.3. The differential algebraic Manin maps

Contrary to the previous subsection, the variations of pure, resp. mixed, Hodge structures that $H^1_{dR}(A)$, resp. $H^1_{dR}(\mathbb{A}_y)$, carry will now play a role. Indeed, the exact sequence

$$0 \longrightarrow \mathbb{1} \longrightarrow H^1_{\mathrm{d}R}(\mathbb{A}_y) \stackrel{\pi}{\longrightarrow} H^1_{\mathrm{d}R}(A) \longrightarrow 0$$

is the de Rham realization of an exact sequence of VMHS, and the \mathcal{O}_{S} module $\Omega := H^0(A, \Omega^1_{A/S})$ is the Fil¹ of the Hodge structure (of weight 1) of $H^1_{dR}(A)$. Now, the Fil¹ of the mixed Hodge structure (of weights 0 and 1) carried by $H^1_{dR}(\mathbb{A}_y)$ projects under π onto Fil¹($H^1_{dR}(A)$), and they actually have the same rank since the pure Hodge structure of the kernel of π has type (0,0). So, there is a canonical section s_{Ω} of π over Ω , and following [13], we will view Ω as a subspace of both $H^1_{dR}(A)$ and, via s_{Ω} , of $H^1_{dR}(\mathbb{A}_y)$.

Of course, s_{Ω} will in general not extend to a \mathcal{D} -section above the D_A module $[\Omega]$ generated by Ω in $H^1_{\mathrm{dR}}(A)$. When this does occur, we will say that the extension $\mathcal{M}_{|[\Omega]}(y)$ of $[\Omega]$ by 1 admits a (D, Fil) -section. More generally, we may consider the pointed set (actually a group) $\mathrm{Ext}_{D,\mathrm{Fil}}([\Omega], 1)$ of isomorphism classes of extensions of $[\Omega]$ by 1 endowed with an \mathcal{O}_S -section above Ω , which admits a forgetful map

$$\mathcal{F}: \operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], \mathbb{1}) \longrightarrow \operatorname{Ext}_{D-\operatorname{mod}}([\Omega], \mathbb{1}).$$

The map $\mathcal{M}_{|[\Omega]} : A(S) \to \operatorname{Ext}_{D-\operatorname{mod}}([\Omega], 1)$ factors through \mathcal{F} (thanks to the section s_{Ω}), and we will see in Theorem 3.1, proof of (iii)(b), that \mathcal{F} is *injective* on the image of A(S) in $\operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], 1)$. In fact, an explicit computation of $\operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], 1)$ should clarify why the kernel of the Manin map μ below contains the kernel of $\mathcal{M}_{|[\Omega]}$, in the spirit of the discussion on $\mu = 0$ and $\bar{\mu} = \bar{0}$ at the end of Section 2.1.1 (see also Section 3.3). But let us come back to the construction of μ .

Via the Gauss–Manin connections, \mathcal{D} acts on $H^1_{dR}(A)$, $H^1_{dR}(\mathbb{A}_y)$, and this defines two maps ϕ , ϕ_y of left \mathcal{D} -modules from $\mathcal{D} \otimes_{\mathcal{O}_S} \Omega$ to $H^1_{dR}(A)$, $H^1_{dR}(\mathbb{A}_y)$,

which commute with the projection π . The image of ϕ is $[\Omega]$, and we denote its kernel by PF (for Picard–Fuchs as in [18]). So, $\mathcal{L} = \sum_i L_i \otimes \omega_i$ lies in PF if and only if $\phi(\mathcal{L}) = \sum_i L_i(D_A)(\omega_i) = 0 \in H^1_{\mathrm{dR}}(A)$. The image of ϕ_y is $i_{[\Omega]}^* \mathcal{M}(y)$. For any \mathcal{L} in PF, $\phi_y(\mathcal{L}) = \sum_i L_i(D_{\mathbb{A}_y})(\omega_i) \in H^1_{\mathrm{dR}}(\mathbb{A}_y)$ lies in the kernel \mathcal{O}_S of π , and we define the Manin map $\mu_{\mathcal{L}} : A(S) \to O_S$ attached to \mathcal{L} by:

$$\mu_{\mathcal{L}}: A(S) \ni y \longmapsto \mu_{\mathcal{L}}(y) := \phi_y(\mathcal{L}) \in O_S,$$

The following commutative diagram illustrates this construction. The section $y \in A(S)$ is given, and the first vertical arrow is the map $\mathcal{L} \to \mu_{\mathcal{L}}(y)$ induced by ϕ_y on PF.

$$\begin{array}{cccc} 0 \longrightarrow PF \longrightarrow \mathcal{D} \otimes \Omega \stackrel{\phi}{\longrightarrow} [\Omega] \longrightarrow 0 \\ & & & & & & & \\ & & & & & & \\ 0 \longrightarrow O_S \longrightarrow \mathcal{M}_{|[\Omega]}(y) \stackrel{\pi}{\longrightarrow} [\Omega] \longrightarrow 0 \\ & & & & & \\ & & & & & \\ 0 \longrightarrow O_S \longrightarrow \mathcal{M}(y) \stackrel{\pi}{\longrightarrow} H^1_{\mathrm{dR}}(A) \longrightarrow 0 \end{array}$$

For any \mathcal{L} in PF, the map $\mu_{\mathcal{L}}$ is additive in y. When \mathcal{L} runs through PF, their collection measures how far $\mathcal{M}_{|[\Omega]}(y)$ is from being trivial in $\operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], \mathbb{1})$. Since the \mathcal{D} -module PF admits a finite number of generators, say $\mathcal{L}_1, \ldots, \mathcal{L}_N$, we may group all the information on PF by defining the differential algebraic Manin map as the map

$$\boldsymbol{\mu}_A := \boldsymbol{\mu} = (\mu_{\mathcal{L}_1}, \dots, \mu_{\mathcal{L}_N}) : A(S) \longrightarrow (\mathbb{G}_a)^N(S).$$

Just like μ_E in Section 1, this a differential algebraic additive morphism, and the initial version of Manin's theorem of the kernel (see [18, Thm. 2], and [13, Thm. 2.1.0]) states that

$$\operatorname{Ker}(\boldsymbol{\mu}) = A_0(\mathbb{C})^{div}.$$

For the intermediate step $\operatorname{Ker}(\mu) = \operatorname{Ker}(\mathcal{M}_{|[\Omega]})$ towards this conclusion, see Theorem 3.1 (iii), which, combined with (ii) and (i), yields the full statement.

To compute the maps $\mu_{\mathcal{L}}$, one needs a concrete vizualization of the extension $H^1_{dR}(\mathbb{A}_y)$. We may interpret it as the exact sequence

$$0 \longrightarrow \mathcal{O}_S \longrightarrow H^1_{\mathrm{d}R}(A/S, Z_y) \xrightarrow{\pi} H^1_{\mathrm{d}R}(A/S) \longrightarrow 0,$$

where the middle term is the relative cohomology with respect to the subscheme Z_y of A/S formed by the union of the image of y and of the zero section: if a relative differential ξ (regular along 0 and y) projects to 0 in $H^1_{dR}(A/S)$, then $\xi = df, f \in K(A)$, is represented by $f(y) - f(0) \in \mathcal{O}_S$. Roughly speaking, $H^1_{dR}(A/S, Z_y)$ is the space of differentials of the 2nd kind on A, modded out by exact forms in the "narrow" sense (df with f(0) = f(y) = 0), while one mods out by all exact forms to get $H^1_{dR}(A/S)$.

For instance, suppose that $\mathcal{L} = L_{\omega} \otimes \omega$, where $\omega \in \Omega$ and $L_{\omega} \in \mathcal{D}$ is the annihilator of ω (viewed in the \mathcal{D} -module $H^1_{\mathrm{dR}}(A/S)$, hence of order $\leq 2g$). Then, an analytic expression for $\mu_{\mathcal{L}}(y)$ is given by

$$\mu_{L_{\omega}\otimes\omega}(y) = L_{\omega}\left(\int_{0}^{y}\omega\right).$$

To get an algebraic expression, we write the extension of ∂ to K(A) and to the differential forms on A_K in terms of an "admissible" set of parameters at 0 and y, as explained in [18, p. 223]. In this case, $\mu_{\mathcal{L}}(y)$ is just f(y) - f(0), where $L_{\omega}(D_{\mathbb{A}_y})(\omega) = \mathrm{d}f$. In general, ∂ does not commute with \int_0^y , and as in Section 1, fudge factors must be added, to take into account differentiation of the boundary, but this suffices to show that as a function of y, $\mu_{\mathcal{L}}$ extends to a differential K-rational additive character of order $\leq 2g$.

This brings us to another type of differential algebraic Manin map, namely: instead of looking at a set of generators of PF as was done in the definition $\boldsymbol{\mu}$, we merely consider the "cyclic" elements of the above type $\mathcal{L}_{\omega} = L_{\omega} \otimes \omega, \omega \in \Omega$. Fixing a basis $\omega_1, \ldots, \omega_q$ of Ω over \mathcal{O}_S , we set

$$\boldsymbol{\mu}_{\Omega}: A(S) \longrightarrow (\mathbb{G}_a)^g(S): y \longmapsto (\mu_{\mathcal{L}_{\omega_i}}(y), i = 1, \dots, g).$$

Clearly, the kernel of $\boldsymbol{\mu}$ is contained in that of $\boldsymbol{\mu}_{\Omega}$. As a consequence of the semi-simplicity of the *D*-module $H^1_{\mathrm{d}R}(A/S)$, we will see in Theorem 3.1 (vi) that in fact

$$\operatorname{Ker}(\boldsymbol{\mu}_{\Omega}) = \operatorname{Ker}(\boldsymbol{\mu}),$$

although $\mathcal{L}_{\omega_1}, \ldots, \mathcal{L}_{\omega_q}$ need not generate the full \mathcal{D} -module PF.

Remark 2.2. — In the spirit of Remark 2.1, but now in the language of differential algebraic groups, here is another presentation of the map μ_{Ω} . Let again \widetilde{A} be the universal vectorial extension of A, equipped with its unique D-group structure, and let W_A be the unipotent part of \widetilde{A} . We have the differential algebraic homomorphism $\partial \ell n_{\widetilde{A}} : \widetilde{A} \to L\widetilde{A}$, surjective over a differential closure of K. Here again, if $\widetilde{y} \in \widetilde{A}$ lifts $y \in A$, the image of \widetilde{y} under $\partial \ell n_{\widetilde{A}}$, now modulo the subgroup $\partial \ell n_{\widetilde{A}}(W_A)$, depends only on y. This gives a surjective differential algebraic homomorphism $\mu'_{\Omega} : A \to L\widetilde{A}/\partial \ell n_{\widetilde{A}}(W_A)$, which is defined over K. This map has the same type of target as μ . Indeed, as pointed out by Pillay in [8, §2.4], the quotient $L\widetilde{A}/\partial \ell n_{\widetilde{A}}(W_A)$ is a unipotent commutative differential algebraic group, and so, by results of Buium and Cassidy, is differential-algebraically isomorphic to some power of \mathbb{G}_a . Moreover, the power (\mathbb{G}_a)^g suffices, so we may view μ'_{Ω} as a version of our map μ_{Ω} . It is shown in [7, Cor. K.3], that at the level of K-points, $\operatorname{Ker}(\mu'_{\Omega}) = A_0(\mathbb{C})^{div}$.

Revisiting Manin's theorem of the kernel

3. Manin kernels

3.1. The theorems of the kernel

We now turn to the promised Theorem 3.1, which (except maybe for (vi), and for the injectivity of \mathcal{F} in the proof of (iii)) is a combination of the work of Manin, Coleman, Chai and André.

We recall the notation of Section 2, including the notation s_{Ω} for the canonical section of $\mathcal{M}(y)$ above Ω . In (iv), (v) and tacitly (vi), $\underline{\omega}$, resp. $\underline{\eta}$, denote a basis $\{\omega_1, \ldots, \omega_g\}$ of Ω , resp. differentials of the 2nd kind $\{\eta_1, \ldots, \eta_g\}$ representing a complement of $\underline{\omega}$ into a basis of $H^1_{\mathrm{dR}}(A/S)$, while $\{\gamma_1, \ldots, \gamma_{2g}\}$ is a basis of the Betti homology $T_B(A)$.

THEOREM 3.1. — Let y be a section of A/S. Then,

- (i) $\operatorname{Ker}(\mathcal{M}) = A_0(\mathbb{C})^{div}$, *i.e.* $\mathcal{M}(y)$ is split if and only if y is a constant section.
- (ii) $\operatorname{Ker}(\mathcal{M}_{|[\Omega]}) = \operatorname{Ker}(\mathcal{M}), i.e. i^*_{[\Omega]} \text{ is injective on the image of } \mathcal{M};$
- (iii) $\operatorname{Ker}(\boldsymbol{\mu}) = \operatorname{Ker}(\mathcal{M}_{|[\Omega]}).$
- (iv) $\mathcal{M}(y) = 0 \Leftrightarrow \int_0^{\hat{y}} (\underline{\omega}, \underline{\eta})$ is a \mathbb{C} -linear combination of the vectors $\int_{\gamma_i} (\underline{\omega}, \underline{\eta}), j = 1, \dots, 2g$, up to addition of an element of $(O_S)^{2g}$.
- (v) $\boldsymbol{\mu}(y) = 0 \Leftrightarrow \int_0^y (\underline{\omega})$ is a \mathbb{C} -linear combination of the vectors $\int_{\gamma_j} (\underline{\omega}), j = 1, \ldots, 2g$.
- (vi) $\operatorname{Ker}(\boldsymbol{\mu}_{\Omega}) = \operatorname{Ker}(\mathcal{M}_{|[\Omega]}).$

So, at long last, the four "Manin kernels"

$$\operatorname{Ker}(\boldsymbol{\mu}) \subset \operatorname{Ker}(\boldsymbol{\mu}_{\Omega}), \quad \operatorname{Ker}(\mathcal{M}) \subset \operatorname{Ker}(\mathcal{M}_{|[\Omega]})$$

coincide: they are all equal to $(A_0(\mathbb{C}))^{\text{div}}$. In particular, they are reduced to the torsion subgroup $A^{\text{tor}}(S)$ when the K/\mathbb{C} -trace of A vanishes

Notice that the first two kernels are a priori much smaller than the last two ones. In the elliptic situation of Section 1 (where $[\Omega]$ is the full $H^1_{dR}(E/S)$), $\operatorname{Ker}(\mathcal{M}) = \operatorname{Ker}(\mathcal{M}_{|[\Omega]})$ consists of those $y \in E(S)$ such that $\mu_E(y) = L(f)$ for some element $f \in O_S$, whereas $\operatorname{Ker}(\mu_E)$ (here obviously equal to $\operatorname{Ker}(\mu_{\Omega})$) consists of those y such that $\mu_E(y)$ is "physically" equal to the zero of O_S .

Notice also that when $[\Omega]$ does not fill up $H^1_{dR}(A/S)$, the third kernel is *a priori* truly smaller than the last one. On the other hand, up to the discrepancy just mentioned between "isomorphic to 0" and "physically 0", the first two ones have the same flavour as the last one: they solely concern the restriction to $[\Omega]$ of $\mathcal{M}(y)$.

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A guide to the proofs of Theorem 3.1

The statement of Theorem 3.1, and the proofs recorded or given below, have logical overlaps, and could be described in a much smoother way. Our aim here is to remain as close as possible to the literature, in particular Manin's original paper [18], Coleman's reformulation [13], Chai's sharpening [12] and André's presentation [2].

Proof of (i). — This formulation of Manin's theorem is due to Coleman [13, Thm. 1.4.3], who gave two proofs, one algebraic, the other analytic. See also [7, Prop. J.2] for a proof in the setting of Remark 2.1. \Box

Proof of (ii). — This is due to Chai, who gives a Hodge theoretical proof at the end of his paper [12]. See also [7, Thm. K.1] for a proof in the language of Remark 2.1. We will discuss in Section 3.2 below Chai's generalization of (ii), where $[\Omega]$ is replaced by any *D*-submodule *V* of $H^1_{dB}(A/S)$.

Proof of (iii). —

(a). — Let us first prove that if $\boldsymbol{\mu}(y) = 0$, then s_{Ω} extends to a (D, Fil) section of $\mathcal{M}_{|[\Omega]}(y)$ (hence to a *D*-section, hence $\mathcal{M}_{|[\Omega]}(y) = 0$). Recall the
maps ϕ, ϕ_y of Section 2.3, and assume that $\mu_{\mathcal{L}}(y) = 0$ for all $\mathcal{L} \in PF$. For win $[\Omega]$, choose $\mathcal{L} \in \mathcal{D} \otimes \Omega$ such that $w = \phi(\mathcal{L})$. If \mathcal{L}' is another choice, then $\mathcal{L} - \mathcal{L}'$ lies in PF, and its image under ϕ vanishes. So, $\widetilde{w} := \phi_y(\mathcal{L}) := \widetilde{s}(w)$ gives a well-defined section \widetilde{s} of π over $[\Omega]$, extending s_{Ω} . And since ϕ and ϕ_y are \mathcal{D} -linear, so is \widetilde{s} .

The converse statement is easy, and the equivalence is essentially Coleman's Proposition 2.1.1 of [13]. But to finish up the proof of (iii), we must show that if the extension $\mathcal{M}_{|[\Omega]}(y)$ admits a \mathcal{D} -section, not necessarily inducing s_{Ω} on Ω , then $\boldsymbol{\mu}(y) = 0$; and so, in the end, it does admit a (D, Fi) section. In other words, the forgetful map \mathcal{F} introduced in Section 2.3 is injective on the image of A(S) in $\mathrm{Ext}_{D,\mathrm{Fil}}([\Omega], \mathbb{1})$.

(b). — Assuming now that $\mathcal{M}_{|[\Omega]}(y) = 0$, let us show that $\boldsymbol{\mu}(y) = 0$. I do not see a direct proof (again because of the discrepancy between physically 0 and isomorphic to 0), but we deduce from (ii) and (i) that y is a constant section and are thereby reduced to the case where $A = A_0$ is defined over \mathbb{C} , with a basis of Ω also defined over \mathbb{C} . Then, by Abel Jacobi (cf. [3, 3.1]), the constant vector $\int_0^y (\underline{\omega})$ is a linear combination over \mathbb{C} (even, over \mathbb{R}) of the vectors $\int_{\gamma_c} (\underline{\omega}), j = 1, \ldots, 2g$.

So, let us assume that there exist complex numbers a_1, \ldots, a_{2g} such that for all $i = 1, \ldots, g$, $\int_0^y \omega_i = \sum_{j=1,\ldots,2g} a_j \int_{\gamma_j} \omega_i$, and let $\mathcal{L} = \sum_{i=1,\ldots,g} L_i \otimes \omega_i$ be an element of *PF*. Then, $\phi_y(\mathcal{L})$ is represented by an exact form df, and $\mu_{\mathcal{L}}(y) = \sum_{i} L_i(\int_0^y \omega_i)$ is equal to

$$\mu_{\mathcal{L}}(y) = \sum_{i} \sum_{j} a_{j} L_{i} \left(\int_{\gamma_{j}} \omega_{i} \right) = \sum_{j} a_{j} \left(\sum_{i} L_{i} \left(\int_{\gamma_{j}} \omega_{i} \right) \right)$$
$$= \sum_{j} a_{j} \int_{\gamma_{j}} \sum_{i} L_{i}(\omega_{i}) = \sum_{j} a_{j} \int_{\gamma_{j}} \mathrm{d}f = 0$$

(for the third equality, recall that ∂ commute with \int_{γ_j}). So indeed, $\mu(y) = 0.$

Proof of (iv). — The collection of these vectors forms a fundamental matrix of solutions for the differential system attached to the Gauss–Manin connection ∇_A on $H^1_{dR}(A/S)$. As said in Section 2.1.1, the condition on the right expresses the fact that the extension ∇_{A_y} of ∇_A by 1 is split. Note that this condition was incorrectly stated in [2, Thm. 1.1.(ii)], where the proviso "up to addition of an element of $(O_S)^{2g}$ " must be added. On the other hand, its Condition (iii) was correctly stated, and does imply the corrected version of (ii) when $[\Omega]$ fills up $H^1_{dR}(A/S)$, bearing in mind the fudge factors due to the derivations of the boundaries of the integrals.

Proof of (v). — (It is essentially Proposition 4 of Manin's paper [18].) If $\mu(y) = 0$, the combination of (iii), (ii) and (i) implies that y is a constant section, and we conclude by Abel–Jacobi. The converse has just been proved in the second part of Point (iii)(b) above.

Proof of (vi). — If $\mathcal{M}_{|[\Omega]}(y) = 0$, $\mu(y) = 0$ by (iii), and in particular, $\mu_{\Omega}(y) = 0$. Conversely, assume that $\mu_{\Omega}(y) = 0$. For any ω_i in a basis of Ω , with annihilator $L_{\omega_i} \in \mathcal{D}$, this implies that the restriction $\mathcal{M}_{|[\omega_i]}(y)$ of $\mathcal{M}_{|[\Omega]}(y)$ to the *D*-submodule $[\omega_i] \simeq \mathcal{D}/\mathcal{D}L_{\omega_i}$ generated by ω_i in $H^1_{\mathrm{dR}}(A/S)$ is split. Now, a fundamental result of Deligne [14, Thm. 4.2.6], states that the *D*-module $H^1_{\mathrm{dR}}(A/S)$ is semi-simple. Consequently, one can speak of the largest *D*-submodule *U* of $H^1_{\mathrm{dR}}(A/S)$ over which the extension $\mathcal{M}(y)$ is split (see for instance [17, §1.2.1], for the dual statement). Since the $[\omega_i]$'s generate $[\Omega], U$ contains $[\Omega]$, and the restriction $\mathcal{M}_{|[\Omega]}(y)$ of $\mathcal{M}(y)$ to $[\Omega]$ is split. \Box

3.2. Chai's theorem

In order to prove Part (ii) of Theorem 3.1, namely that $\mathcal{M}(y)$ splits if (and clearly only if) its restriction to $[\Omega]$ does, one can assume that the abelian scheme A/S is geometrically simple. Indeed, for A isogenous to $A_1 \times A_2$, one has in obvious notation: $\mathcal{M}_{|\Omega|} \simeq \mathcal{M}_{|\Omega_1|} \times \mathcal{M}_{|\Omega_2|}$, and similarly with

 $\mathcal{M}_{A_1 \times A_2}$. So in this subsection, we will assume that A/S is geometrically simple. In particular, either A/S is constant, or its K/\mathbb{C} -trace A_0 vanishes. Chai then proposed in [12] the following generalization of his Theorem 3.1 (ii).

THEOREM 3.2. — Let A/S be a simple abelian scheme, let $y \in A(S)$ be a section, and let $i_V : V \hookrightarrow H^1_{dR}(A)$ be a non-zero D-submodule of $H^1_{dR}(A)$. Assume that $i_V^*(\mathcal{M}(y)) := \mathcal{M}_{|V}(y) \in \operatorname{Ext}_{D-\operatorname{mod}}(V, \mathbb{1})$ is split. Then, $\mathcal{M}(y)$ is split.

Unfortunately, the proof given in [12] relies on the assumption that if the simple abelian scheme A/S is not constant, then the *D*-module $H^1_{dR}(A)$ is irreducible. This is not always the case, as shown by Deligne's counterexample in [16]. In [5] (see also [11]), I pointed out this gap, and proposed a way to fix it. This corrected proof, reproduced in its original form, is the content of what follows. For other presentations, see [6, Formulae (2'), (2*) (in the setting of Remark 1)], and André's report [2], which incorporates a proof of his results [1] on algebraic independence.

It will here be more convenient to return to the covariant view-point of Section 2.1.2. So, given a *D*-submodule *V* of $T_{dR}(A)$ strictly contained in $T_{dR}(A)$, i.e. with a non-trivial projection $p := p_V : T_{dR}(A) \to T_{dR}(A)/V$, we must show that if the *D*-module

$$p_*(T_{\mathrm{d}R}(\mathbb{A}_y)) = T_{\mathrm{d}R}(\mathbb{A}_y)/V \in \mathrm{Ext}_{D-\mathrm{mod}}(\mathbb{1}, T_{\mathrm{d}R}(A)/V)$$

is a split extension, then $T_{dR}(\mathbb{A}_y) \in \operatorname{Ext}_{D-\operatorname{mod}}(\mathbb{1}, T_{dR}(A))$ is split.

Proof. — Fix a point $s \in S$, and let $T_{A,s}, T_{A,y,s}$ be the fiber at s of the local systems $T_B(A), T_B(\mathbb{A}_y)$ (tensored with \mathbb{Q}). These fibers define an extension

 $0 \longrightarrow T_{A,s} \longrightarrow T_{A,y,s} \longrightarrow \mathbb{Q} \longrightarrow 0$

of representations over \mathbb{Q} of the fundamental group $\pi_1(S, s)$. Here, \mathbb{Q} is the trivial representation. Since all our differential equations are fuchsian at the missing points of S, this extension of monodromy representations splits if and only if $T_{dR}(\mathbb{A}_y)$ splits.

Chai's argument [12] now goes as follows. We consider the following algebraic groups over \mathbb{Q} :

- $\widetilde{G} \subset GL(T_{A,y,s})$ is the Q-Zariski closure of the image of π_1 acting on $T_{A,y,s}$; this group depends on y;
- $G \subset GL(T_{A,s})$ is the Q-Zariski closure of the image of π_1 acting on $T_{A,s}$; by [14], the (connected component G^0 of the) group G is a reductive group;
- N = kernel of the natural map $\widetilde{G} \to G$; the construction below shows that N is abelian, hence acted upon naturally by $\widetilde{G}/N = G$.

Fixing apoint $\widetilde{\lambda} \in T_{A,y,s}$ above $1 \in \mathbb{Q}$, and considering $g\widetilde{\lambda} - \widetilde{\lambda}$, we obtain a cocycle $\xi_y \in H^1(\widetilde{G}, T_{A,s})$, whose restriction to N

$$\xi(y): N \longrightarrow T_{A,s}$$

is a *G*-equivariant injective morphism between vectorial groups over \mathbb{Q} . So, N identifies with a $\mathbb{Q}[G]$ -submodule of $T_{A,s}$. Since G is reductive, N = 0 if and only if the extension $T_{A,y,s}$ (equivalently $T_{dR}(\mathbb{A}_y)$) splits: indeed, $T_{A,y,s}$ becomes a representation of G if N = 0.

By hypothesis, V is a strict D-submodule of $T_{dR}(A)$ such that $T_{dR}(\mathbb{A}_y)/V$ splits as a D-module extension of 1 by $T_{dR}(A)/V$. Since the C-local system T(V) of horizontal vectors of V needs not be generated by its intersection with the Q-structure $T_B(A)$, we extend the scalars to C, and consider the projection of N to $(T_{A,s} \otimes \mathbb{C})/(T(V)_s)$. Since $T_{dR}(\mathbb{A}_y)/V$ splits, one easily checks that this projection vanishes. So, $N \otimes \mathbb{C} \subset (T(V))_s$ does not fill up $T_{A,s} \otimes \mathbb{C}$, and N must be a strict $\mathbb{Q}[G]$ -submodule of $T_{A,s}$.

If $T_{A,s}$ is an irreducible $\mathbb{Q}[G]$ -module (equivalently, if $T_{dR}(A)$ is an irreducible *D*-module), this implies that N = 0, hence $T_{dR}(\mathbb{A}_y)$ splits, as was to be shown. But as said above, this hypothesis does not always hold, even if the simple abelian scheme *A* is not constant. To fill up this gap, we will now appeal to André's normality theorem on the Mumford–Tate groups attached to *S*-1-motives (see [1], and the Remark at the end of [2, §1.5] for a motivic presentation).

For any $s \in S$, we denote by $MT_{A,s} \subset GL(T_{A,s})$ (resp. $MT_{A,y,s} \subset GL(T_{A,y,s})$) the Mumford–Tate group of the Hodge structure (resp. mixed HS) attached to A (resp. A_y). These are connected algebraic groups over \mathbb{Q} , which satisfy the following facts:

- (1) ([1, Lem. 4]): there is a meager subset of S whose complement S_0 is pathwise connected, and such that $MT_{A,y,s}$ (hence $MT_{A,s}$) is locally constant over S_0 .
- (2) ([1, Thm. 1]) Let \tilde{G}_s^0 be the connected component of the (monodromy) group called \tilde{G} above. Then, for any $s \in S_0$, \tilde{G}_s^0 is a normal subgroup of $MT_{A,y,s}$. Actually, [1] further shows that \tilde{G}_s^0 is contained in the derived group of $MT_{A,y,s}$, but we will not need this sharpening.

After extension to a finite cover of S, we may assume that G, hence G are already connected. We make this assumption from now on, and proceed to finish up the proof of Theorem 3.2 (in its dual version). We fix a base point s in S_0 as in Fact (1), yielding the algebraic groups

• \widetilde{G} as above, normal in $\widetilde{MT} := MT_{A,y,s}$ by Fact (2);

- G as above, normal in $MT := MT_{A,s}$;
- N as above, contained in the kernel

$$NT = \{g \in MT, g(T_{A,y,s}) \subset W_{-1}(T_{A,y,s}) = T_{A,s}\}$$

of the natural map $\widetilde{MT} \to MT$. Fixing apoint $\widetilde{\lambda} \in T_{A,y,s}$ above $1 \in \mathbb{Q}$, and considering $g\widetilde{\lambda} - \widetilde{\lambda}$, we obtain a cocycle $\Xi_y \in H^1(\widetilde{MT}, T_{A,s})$, whose restriction $\Xi(y) : NT \to T_{A,s}$ to NT shows that NT is abelian (and is a $\mathbb{Q}[MT]$ -submodule of $T_{A,s}$). Notice for later use that the restriction of $\Xi_y, \Xi(y)$, to \widetilde{G}, N , coincide with the maps $\xi_y, \xi(y)$, of the previous paragraph.

As recorded, \widetilde{G} is normal in \widetilde{MT} . We will now show that N too is normal in \widetilde{MT} . Extending the scalars to \mathbb{C} , it suffices to show that $N_{\mathbb{C}}$ is normal in $\widetilde{MT}_{\mathbb{C}}$. Since $G_{\mathbb{C}}$ is reductive and $N_{\mathbb{C}}$ is abelian, $N_{\mathbb{C}}$ is the unipotent radical of $\widetilde{G}_{\mathbb{C}}$, i.e. the (unique) maximal connected unipotent normal subgroup of $\widetilde{G}_{\mathbb{C}}$. Therefore, $N_{\mathbb{C}}$ is fixed under any automorphism of $G_{\mathbb{C}}$, and in particular, under all outer automorphisms $Int(g), g \in \widetilde{MT}(\mathbb{C})$ of $\widetilde{G}_{\mathbb{C}}$ that the normality of \widetilde{G} in \widetilde{MT} provides. So, $N_{\mathbb{C}}$ is indeed normal in $\widetilde{MT}_{\mathbb{C}}$. And since the abelian group NT acts trivially on its subgroup N, the action of \widetilde{MT} on Nby conjugation induces an action of $\widetilde{MT}/NT = MT$.

We now see that the \mathbb{Q} -morphism

$$\xi(y) = (\Xi_y)_{|N} : N \longrightarrow T_{A,s}$$

is equivariant not only under G, but also under the full action of MT. So, N identifies with a MT-submodule of $T_{A,s}$. Now, $T_{A,s}$ is irreducible as a $\mathbb{Q}[MT]$ -module, since our choice of s forces $\operatorname{End}_{MT}(T_{A,s}) = \operatorname{End}(A_s) = \operatorname{End}(A/S)$, and we conclude that either N = 0 (implying as before that $T_{\mathrm{d}R}(\mathbb{A}_y)$ is split), or that $N = T_{A,s}$. As we already saw, the latter case prevents the existence of any non-trivial projection p such that $p_*(T_{\mathrm{d}R}(\mathbb{A}_y))$ splits, unless $T_{\mathrm{d}R}(\mathbb{A}_y)$ itself is split. \Box

3.3. Manin images

Now that the kernels of the Manin maps have been described, we will say a few words on their images. Since their targets are \mathbb{C} -vector spaces, it is natural to study their \mathbb{C} -linear extensions. The following proposition, borrowed from [8], shows how differently the differential algebraic and cohomological Manin maps behave in this respect. Proposition 3.3. —

- (i) There exists a simple traceless abelian scheme A/S such that the Clinear extension μ'_Ω ⊗ 1 : A(S) ⊗ C → (O_S)^g of μ'_Ω is not injective.
- (ii) If A/S is a traceless abelian scheme, the \mathbb{C} -linear extension $\mathcal{M} \otimes 1$: $A(S) \otimes \mathbb{C} \to T_{\mathrm{dR}}(A)(S)/D_A(T_{\mathrm{dR}}(A)(S))$ of \mathcal{M} is injective.

Proof. — (See [8, Prop. 2.14 and 2.15, and their proofs in §5].) The counterexample for (i) is an abelian scheme of relative dimension 4, whose $H^1_{dR}(A/S)$ strictly contains its D_A -submodule [Ω]. The proofs use the settings of Remarks 1 and 2.

Let me close with a tentative approach to the image of the maps $\mu_{\Omega}, \mu'_{\Omega}$: it is tempting to interpret their target $(O_S)^g$ as the Lie algebra Ω^{\vee} of A/S. However, the map $\Omega \to O_S$ deduced from our association $\omega \mapsto \mathcal{L}_{\omega} = L_{\omega} \otimes \omega$, composed with ϕ_u :

$$\{\omega \in \Omega\} \longrightarrow \{\mathcal{L}_{\omega} \in PF\} \xrightarrow{\phi_y} \{\mu_{\mathcal{L}_{\omega}}(y) \in O_S\}$$

is seldom additive in ω ([13, Prop. 2.1.3] does provide an O_S -linear map $\Omega \to PF \xrightarrow{\phi_y} O_S$, but only under the condition that the Kodaira map has maximal rank, which implies that $[\Omega] = H^1_{dR}(A/S)$). In any case, $\operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], 1)$ should be computable in terms of $[\Omega]^{\vee}$ (or rather, its quotient Ω^{\vee}), just like $\operatorname{Ext}_{D-\operatorname{mod}}([\Omega], 1)$ is the quotient of $[\Omega]^{\vee}(S)$ by $D_A([\Omega]^{\vee}(S))$. This would give a concrete description of the forgetful map \mathcal{F} , and a direct link between a differential algebraic map of the type μ_{Ω} , now with values in $\operatorname{Ext}_{D,\operatorname{Fil}}([\Omega], 1)$, and the cohomological map $\mathcal{M}_{|[\Omega]}$.

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